MARAM SAKR

1470 Sand Hill Rd, Palo Alto, CA, USA 94304 Email: maram.sakr@ubc.ca Citizenship: Canadian

RESEARCH INTERESTS

I am an experimental roboticist working at the intersection of robotics, machine learning, and human-robot interaction. In particular, I focus on enabling everyday users to intuitively and efficiently program robots. My research investigates the challenges faced by potential users of programmable robots and develops interaction mechanisms, learning algorithms, and interfaces to enhance the efficiency and effectiveness of human-robot interaction.

EDUCATION

University of British Columbia Monash University Joint Ph.D., in Mechanical, Electrical and Computer Systems Engineering Advisors: Prof. Machiel Van der Loos, Prof. Dana Kulić and Prof. Elizabeth Croft. Cumulative GPA: 4.33	Vancouver, Canada Melbourne, Australia Fall 2017 – Present ¹
Johns Hopkins University Visiting Graduate Scholar, in Computer Science Department Advisor: Prof. Chien-Ming Haung	Baltimore, MD, USA 2022
 Simon Fraser University M.Sc., in Engineering Science Thesis: Feasibility of Using Force Myography for Estimating Hand Force and Wrist To Advisor: Prof. Carlo Menon Cumulative GPA: 4.08 	Burnaby, Canada Fall 2016 – Fall 2017 rque
Mansoura University B.Sc., in Computers and Systems Engineering Distinction with honor degree, <i>Total grade:</i> 88.48% - ranked 3 rd <i>Thesis/Graduation Project:</i> One-Eved Self-Learning Arm Bobot	Mansoura, Egypt 2007 - 2012

ACADEMIC HONORS & AWARDS

- NSERC Postdoctoral Fellowship (\$140,000 CAD), ranked first in Canada in the Computing Sciences committee. 2025 2027
- RSS Pioneer: I was selected to participate in the Robotics: Science and Systems (RSS) Pioneers Workshop, a highly selective workshop, bringing together a cohort of the world's top early career researchers in robotics. 2023
- Nominee for NSERC and L'Oréal-UNESCO for Women in Science award.
- Canada Graduate Scholarships Michael Smith Foreign Study Supplements (CGS-MSFSS) from NSERC (\$6,000 for six months). 2022

2023

- Alexander Graham Bell Canada Graduate Scholarship from NSERC (\$35,000 per year for three years), ranked first in Canada in the Computing Sciences committee. 2020 - 2023
- President's Academic Excellence Initiative PhD Award at the University of British Columbia. 2020 2023

¹I was on maternity leave for 18 months as detailed in section CAREER INTERRUPTIONS.

- HRI Pioneer: I was selected to participate in the Human-Robot Interaction (HRI) Pioneers Workshop, a highly selective workshop seeking to foster creativity, communication, and collaboration across Human-Robot Interaction. 2021
- British Columbia Government Scholarship (BCGS) (\$15,000). 2020
- Monash Research Scholarship (\$25,295). 2019 2023
- Monash International Postgraduate Research Scholarship (\$42,340). 2019 2023
- The Faculty of Applied Science Graduate Award at the University of British Columbia, three times. 2018-2021
- The International Tuition Award at the University of British Columbia, two times. 2017 2019
- The Provost Doctoral Entrance Award for Women at the University of Waterloo (\$5,000) (declined). 2017
- The Graduate Fellowship at Simon Fraser University (\$6,500). Summer 2017
- My graduation project was one of the winning projects in the 6^{th} Annual Egypt's Young Entrepreneurs Competition of Injaz Egypt and we received a seed fund of 60,000 Egyptian pounds from ExxonMobil Egypt. 2012
- My graduation project won the Young Innovator award from Nahdet El Mahrousa Association and a prize of 6000 Egyptian Pounds, which is given to the best bachelor theses in Egypt. 2012
- Distinction Award from the Faculty of Engineering, Mansoura University, Egypt, five times. 2007 2012

WORK/RESEARCH EXPERIENCE

Johns Hopkins University Computer Science Department

Visiting Graduate Scholar

Working with Prof. Chien-Ming Huang at Intuitive Computing Lab. Conducting research in the area of Robot Learning from Demonstration.

University of British Columbia Mechanical Engineering

Research Assistant

Working with Prof. Machiel Van der Loos at the Collaborative Advanced Robotics and Intelligent Systems lab (CARIS) at the University of British Columbia, Prof. Elizabeth Croft at the University of Victoria, and Prof. Dana Kulić at Monash University. Conducting research in the area of Human-Robot Interaction and Robot Learning from Demonstration.

Simon Fraser University School of Engineering Science

Research Assistant

Working with Prof. Carlo Menon at Menrva lab. Conducting research in the area of Human-Robot Interaction, Bio-Signals Processing and Machine Learning.

Simon Fraser University School of Computing Science

Research Assistant

Working with Prof. Mohamed Hefeeda at the Network Systems Lab. Conducting research in the area of Automation and Control systems, and Cloud Computing.

Vancouver, Canada

Baltimore, MD, USA January 2022 - June 2022

Fall 2017 - Dec. 2023

Burnaby, Canada

Fall 2015 - Fall 2017

Burnaby, Canada Spring 2015 - Fall 2015

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EduTKs (Educational Toys and Kits) Co-founder

Startup that specializes in designing and manufacturing creative educational toys and electronic kits for students.

CAREER INTERRUPTIONS

I was on maternity leave from January to August 2019 after the birth of my first child, and again from November 2022 to August 2023 after the birth of my second child.

TECHNICAL SKILLS

Operating Systems: Linux, Windows, macOS

Programming: Python, C++, C#, Matlab/Simulink, ROS (ROS Control, Rviz, Gazebo, MoveIt!)

Hardware: PR2, KUKA iiwa, UR5, Barrett WAM, da Vinci Surgical robot, Kinova Gen2, Kinova Gen3, Robotiq grippers, Microsoft HoloLens 1, Microsoft Hololens 2

Word processing: LATEX, Microsoft Office

SELECTED PUBLICATIONS

Full list Google Scholar JOURNAL ARTICLES

- Maram Sakr, Logan Zhang, Benjamin Li, Haomiao Zhang, H.F. Machiel Van der Loos, Dana Kulić and Elizabeth Croft. "*How Can Everyday Users Teach Robots Efficiently from Demonstrations?*" Submitted to the ACM Transactions on Human-Robot Interaction.
- Joosun Lee, **Maram Sakr**, Taeyhang Lim, H.F. Machiel Van der Loos, Wansoo Kim "Intuitive Augmented Reality Interface for Non-Expert Robot Programming" Submitted to IEEE Robotics and Automation Letters.
- Maram Sakr, Zexi Jesse Li, H.F. Machiel Van der Loos, Dana Kulić, and Elizabeth Croft. "Quantifying Demonstration Quality for Robot Learning and Generalization", IEEE Robotics and Automation Letters, 7(4), pp.9659-9666, 2022 [Also presented at the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, October 2022].
- Wesley P. Chan, Geoffrey Hanks, **Maram Sakr**, Tiger Zuo, H.F. Machiel Van der Loos, and Elizabeth Croft. "Design and Evaluation of a Wearable Augmented Reality Interface for Human-Robot Teams Collaborating in Physically Shared Manufacturing Tasks", ACM Transactions on Human-Robot Interaction (THRI), 11(3), pp.1-19, 2022.
- Jonathan F. Lin, Pamela Carreno-Medrano, Mahsa Parsapour, **Maram Sakr** and Dana Kulić." *Objective learning from human demonstrations*", Annual Reviews in Control, 2021.
- Maram Sakr, Xianta Jiang, and Carlo Menon. "Estimation of User-applied Isometric Force/Torque using Upper Extremity Force Myography", Frontiers in Robotics and AI, 6(120), 2019.
- Alaa Eldin Abdelaal, Maram Sakr, Apeksha Avinash, Shahed Khan Mohammed, Armaan Kaur Bajwa, Mohakta Sahni, Soheil Hor, Sidney Fels, Septimiu E. Salcudean. "Play Me Back: A Unified Training Platform for Robotic and Laparoscopic Surgery", IEEE Robotics and Automation Letters, 4(2), pp.554-561, 2018. [Also presented at the IEEE International Conference on Robotics and Automation (ICRA), Montreal, QC, Canada, May 2019].

PEER-REVIEWED CONFERENCE PUBLICATIONS

- Rajat Kumar Jenamani, Priya Sundaresan, **Maram Sakr**, Tapomayukh Bhattacharjee, Dorsa Sadigh. "FLAIR: Feeding via Long-Horizon Acquisition of Realistic dishes", The Robotics: Science and Systems conference.
- Delun Chen, **Maram Sakr**, Kyle Ah Von, Patrick Thangarajah, and H.F. Machiel Van der Loos. "Enhancing Human-Robot Collaboration in CFRP Manufacturing: Gripper Force Feedback via LED Cues", Submitted to the ACM/IEEE International Conference on Human-Robot Interaction.
- Calvin Z. Qiao, Maram Sakr, Katharina Muelling, and Henny Admoni. "Learning from Demonstration for Real-Time User Goal Prediction and Shared Assistive Control", IEEE International Conference on Robotics and Automation (ICRA), 2021.
- Maram Sakr, Martin Freeman, H.F. Machiel Van der Loos, Elizabeth Croft. "Training Human Teacher to Improve Robot Learning from Demonstration: A Pilot Study on Kinesthetic Teaching", IEEE International Conference on Robot and Human Interactive Communication (RO-MAN), 2020.
- Wesley P. Chan, Geoffrey Hanks, Maram Sakr, Tiger Zuo, H.F. Machiel Van der Loos, and Elizabeth Croft. "An Augmented Reality Human-Robot Physical Collaboration Interface Design for Shared, Large-Scale, Labour-Intensive Manufacturing Tasks", IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), pp. 11308-11313.
- Maram Sakr, and Carlo Menon. "Exploratory Evaluation of the Force Myography (FMG) Signals Usage for Admittance Control of a Linear Actuator", IEEE RAS/EMBS International Conference on Biomedical Robotics and Biomechatronics (BioRob), 2018.
- Maram Sakr, and Carlo Menon. "On the estimation of isometric wrist/forearm torque about three axes using Force Myography", IEEE RAS/EMBS International Conference on Biomedical Robotics and Biomechatronics (BioRob), 2017.
- Maram Sakr and Carlo Menon. "Study on the Force Myography Sensors Placement for Robust Hand Force Estimation", IEEE International Conference on Systems, Man, and Cybernetics (SMC), 2017.

PEER-REVIEWED WORKSHOP PUBLICATIONS

- Maram Sakr. "Towards an Efficient Teaching by Demonstration Framework for Robot Learning", Companion of the Robotics: Science and Systems (RSS), RSS Pioneers workshop, July 2023. (Acceptance rate: ~ 22%)
- Maram Sakr, H.F. Machiel Van der Loos, Dana Kulić and Elizabeth Croft. "What Makes a Good Demonstration for Robot Learning Generalization?", Companion of the ACM/IEEE International Conference on Human-Robot Interaction (HRI), HRI Pioneers Workshop, March 2021. (Acceptance rate: ~ 24%)

THESES

- Maram Sakr, "Feasibility of Using Force Myography for Estimating Hand Force and Wrist Torque". M.Sc. Thesis, School of Engineering Science, Faculty of Applied Sciences, Simon Fraser University, Burnaby, BC, Canada. October 2017.
- Maram Sakr et. al. One-Eyed Self-Learning Arm Robot. B.Sc. Thesis, Computers and Systems Engineering Department, Faculty of Engineering, Mansoura University, Mansoura, Egypt. June 2012.

TEACHING EXPERIENCE

Mansoura University Computers and Systems Engineering Department CSE 3116: Control Engineering CSE 3215: Measurement Devices & Sensors CSE 3221: Statistical Applications CSE 3424: Elective course "Microprocessor" UNC 144: Decision support system

MENTORSHIP

• Taeyhang (Jennette) Lim, MASc. student at Hanyang University, South-I	Korea Fall 2023
• Joo Sun Lee, PhD student at Hanyang University, South-Korea	Fall 2023
• Alexander Calvert, Undergraduate Student, Electrical and Computer E Summer 2023 - Fall 2023	ngineering, Monash University
• Illya Danilevitch, Undergraduate Student, Mechanical Engineering, UBC	Summer 2023
• Qiwu (Angie) Zhang, Undergraduate Student, Electrical and Computer E Present	ngineering, UofT Fall 2022 -
• Emmanuel Ochieng, Undergraduate Student, Cognitive Science, JHU	Fall 2022
• Raiaan Khan, Undergraduate Student, Mechanical Engineering, UBC	Summer 2022
• Priydev Singh, Undergraduate Student, Mechanical Engineering, UBC	Summer 2022
• Chloe Donelan, Undergraduate Student, Computer Science, JHU	Spring 2022
• Kyoungjin Lim, Undergraduate Student, Computer Science, JHU	Spring 2022
• Benji Li, Undergraduate Student, Mechanical Engineering, UBC	Summer 2021 - Spring 2022
• Delun Chan, MASc Student, Mechanical Engineering, UBC	Spring 2021 - Fall 2023
• Logan Zhang, Undergraduate Student, Mechanical Engineering, UBC	Fall 2020 - Summer 2022
• Haomiao Zhang, MASc Student, Mechanical Engineering, UBC	Spring 2020 - Present
- Megan Farn, Undergraduate Student, Mechanical Engineering, UBC	Summer 2021
• Nicholas Qu, Undergraduate Student, Mechanical Engineering, University 2021	of Waterloo Fall 2020 - Spring
• Jesse Li, Undergraduate Student, Mechanical Engineering, UBC	Summer 2020 - Summer 2021
• Sophie Lin, Undergraduate Student, Mechanical Engineering, UBC	Summer 2020 - Spring 2021
• Sameer Todkar, MEng, Mechanical Engineering, UBC	Fall 2020 - Spring 2021
• Yiyi Yan, Undergraduate Student, Mechanical Engineering, UBC	Spring 2020 - Summer 2020
• Martin Freeman, Undergraduate Student, Mechanical Engineering, UBC	Fall 2018 - Summer 2019
• Yi Jui Lee, MASc, Biomedical Engineering, UBC	Summer 2018 - Summer 2019
• Waleed Uddin, MEng, Mechanical Engineering, UBC	Summer 2018 - Spring 2019

SERVICE

- Program chair at the RSS Pioneers 2024.
- Reviewer at CREATE-U program at Mechanical Engineering, UBC. (Summer 2023)
- Panelist at RSS 2021 Workshop on Accessibility of Robot Programming and the Work of the Future

- Reviewer at:
 - Robotics: Science and Systems (RSS 2023)
 - IEEE Robotics and Automation Letters (2022, 2023, 2024)
 - IEEE International Conference on Robot & Human Interactive Communication (RO-MAN 2022)
 - IEEE/ASME Transactions on Mechatronics (2021, 2022)
 - Frontiers in Physiology Journal (2021)
 - The Robotics: Science and Systems conference (RSS 2021)
 - The International Journal of Computers in Industry (2021)
 - IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2020, 2022)
 - ACM/IEEE International Conference on Human-Robot Interaction (HRI)(2020, 2021, 2022 and 2023)
 - IEEE Haptics Symposium (2020)
 - IEEE RAS/EMBS International Conference on Biomedical Robotics and Biomechatronic (BioRob 2018)
- Volunteer at the organization of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2017)
- Volunteer at the organization of ROSCon 2017 (the main conference for the developers of Robot Operating System (ROS))

INVITED TALKS

- "Improving Learning from Demonstrations by Improving Teaching" at Stanford University, September 2023.
- "Quantifying Demonstration Quality for Robot Learning and Generalization" at Johns Hopkins University 2022.
- "What Makes a Good Demonstration for Robot Learning Generalization?" at RSS 2021 Workshop on Accessibility of Robot Programming and the Work of the Future.

ADDITIONAL TRAINING

University of British Columbia The Instructional Skills Workshop (ISW))

This workshop was a 4-day hands-on, intensive teaching course that combines an emphasis on learning evidence and theory-based approaches to teaching and learning.

Monash University

The Robotic Vision Summer School (RVSS)

RVSS designed by the Australian Centre for Robotic Vision. It focuses on fundamental and advanced topics in computer vision and robotics. Through invited lectures, hands-on demonstrations, workshops and miniprojects, the purpose of this summer school is to help researchers familiarize themselves with cutting-edge research in this field.

IVADO and The University of Montreal The 5th Deep Learning Winter School

This winter school was a five-day hands-on, and intensive course in Deep Learning including the fundamental aspects, different applications and future trends.

Vancouver, Canada December 2021

February 2021

Melbourne, Australia

Montreal, Canada December 2019

Simon Fraser University The International Teaching Assistants Program

This program was 10-week intensive seminars and workshops that combines an emphasis on learning evidence and theory-based approaches to teaching and learning.

VOLUNTEERING AND OUTREACH

- Member at the counselling team at Egypt Scholars Inc. where we provide mentorship to current and prospective students regarding studying abroad, hunting scholarships and admission requirements June 2016 Present
- Member of Quality and Reliability unit that aims to improve the education quality in Faculty of Engineering, Mansoura University, Egypt 2013 2015
- Member of the scientific community in my department at Mansoura University 2012 2015